

1 LAQ = 8 MARKS

7. OSCILLATIONS

- SHM • Simple Pendulum • Simple Harmonic Oscillator
- Reference Circle • T.E & K.E of SHM

SMART SYNOPSIS

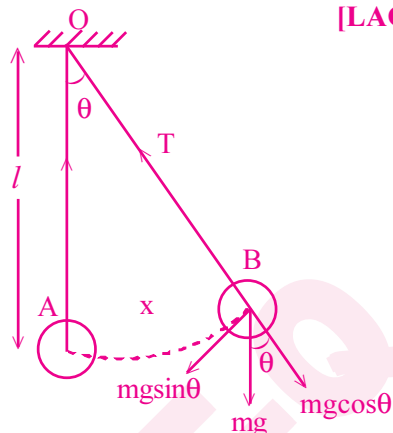
- Periodic Motion** is the motion that repeats itself at 'regular intervals of time.'
Ex: Motion of a pendulum in a wall clock; revolution of Earth around the Sun.
- Oscillation** in simple words is 'To & Fro' motion .
If frequency is very small, we call it an oscillation. **Ex:** Oscillation of a branch of tree.
If the frequency is high, we call it a vibration. **Ex:** Prongs of a tuning fork.
- Harmonic motion** is a 'to & fro' motion with displacement in sinewave pattern.
- Simple Harmonic Motion(SHM)** of a body is a harmonic periodic motion in which the body moves about a mean (equilibrium) position, and the restoring force (or acceleration) always directed towards the mean position and is proportional to its displacement.
Ex : Oscillations of a simple pendulum with small displacement,
motion of a loaded spring which is stretched and released.
- Expression for the Time period of a simple pendulum:**
If l is the length of simple pendulum, then time period $T = 2\pi\sqrt{\frac{l}{g}}$
Note 1: $T \propto \sqrt{l}$; $T \propto \frac{1}{\sqrt{g}}$ **Note 2 :** Frequency $n = \frac{1}{T}$. Hence $n \propto \frac{1}{\sqrt{l}}$; $n \propto \sqrt{g}$
Note 3 : Time period is independent of the "mass of the bob" and "amplitude"
- Seconds pendulum** is a pendulum with time period is 2 seconds .
- Law of conservation of energy :** During the oscillations of a simple pendulum, the total energy remains constant. $PE + KE = \text{constant}$
- The **force constant (k)** of a spring is the restoring force produced per unit displacement of the body from its mean position.

Formula : $k = \frac{F}{x}$ **SI unit:** Nm^{-1} .

Imp.Formulae**I. Simple Pendulum :**

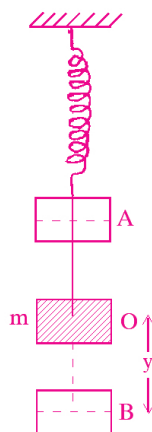
[LAQ 2]

- (i) Time period of a simple pendulum $T = 2\pi\sqrt{\frac{l}{g}}$
- (i) Time period of a seconds pendulum is $T=2s$
- (ii) Length of Seconds pendulum $l = \frac{g}{\pi^2} \approx 1m$

**II. Loaded Spring:**

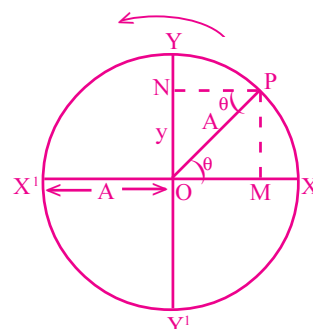
[LAQ 4]

- (i) Time period $T = \frac{2\pi}{\omega} = \frac{2\pi}{\sqrt{\frac{k}{m}}} = 2\pi\sqrt{\frac{m}{k}}$
- (ii) Frequency $n = \frac{1}{T} = \frac{1}{2\pi}\sqrt{\frac{k}{m}}$

**III. Reference Circle (Simple Harmonic Oscillator) :**

[LAQ 1 & 3]

- (i) Displacement $y = A \sin(\omega t)$
- (ii) Velocity $v = A\omega \cos \omega t$ (or) $v = \omega \sqrt{A^2 - y^2}$
- (iii) Acceleration $a = -\omega^2 y$
- (iv) $KE = \frac{1}{2}m\omega^2(A^2 - y^2)$
- (v) $PE = \frac{1}{2}m\omega^2 y^2$
- (vi) $TE = \frac{1}{2}m\omega^2 A^2$



1. SIMPLE HARMONIC MOTION (SHM)

SHM of a body is a harmonic periodic motion in which the body moves about a mean (equilibrium) position, and the restoring force (or acceleration) always directed towards the mean position and is proportional to its displacement.

Ex :

- Oscillations of a simple pendulum with small displacement.
- Motion of a loaded spring which is stretched and released.

2. TIME PERIOD OF A SIMPLE PENDULUM

$$T = 2\pi \sqrt{\frac{l}{g}}$$

3. SECONDS PENDULUM

A pendulum with time period is 2 seconds.

5. THE FORCE CONSTANT (k) OF A SPRING

is the restoring force produced per unit displacement of the body from its mean position.

Formula :

$$k = \frac{F}{x}$$

SI unit: Nm^{-1} .

4. LAW OF CONSERVATION OF ENERGY :

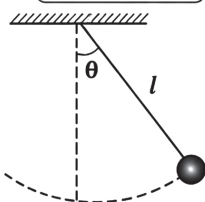
During the oscillations of a simple pendulum, the total energy remains constant.

$$\text{PE} + \text{KE} = \text{constant}$$

**7. OSCILLATIONS
CONCEPTS & FORMULAS****6. SIMPLE PENDULUM**

(i) Time period of a simple pendulum

$$T = 2\pi \sqrt{\frac{l}{g}}$$



(ii) Time period of a seconds pendulum is $T = 2\text{s}$

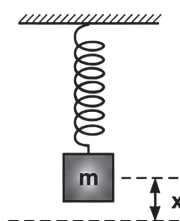
(iii) Length of Seconds pendulum

$$l = \frac{g}{\pi^2} \approx 1 \text{ m}$$

7. LOADED SPRING

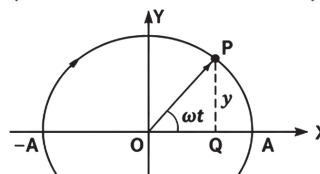
(i) Time period

$$T = 2\pi \sqrt{\frac{m}{k}} = \frac{2\pi}{\omega} = \frac{2\pi}{\sqrt{\frac{k}{m}}} = \frac{2\pi}{\omega}$$



(ii) Frequency

$$n = \frac{1}{T} = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$$

**8. REFERENCE CIRCLE
(SIMPLE HARMONIC OSCILLATOR)**

- (i) Displacement $y = A \sin(\omega t)$
- (ii) Velocity $v = A \omega \cos \omega t$
(or) $v = \omega \sqrt{A^2 - y^2}$
- (iii) Acceleration $a = -\omega^2 y$
- (iv) KE $= \frac{1}{2} m \omega^2 (A^2 - y^2)$
- (v) PE $= \frac{1}{2} m \omega^2 y^2$
- (vi) TE $= \frac{1}{2} m \omega^2 A^2$