



MARCH -2023(AP)

PREVIOUS PAPERS

IPE: MARCH-2023(AP)

Time : 3 Hours

MATHS-1A

Max.Marks : 75

SECTION-A

I. Answer ALL the following VSAQ:

10 × 2 = 20

1. If $f(x) = 2x - 1$, $g(x) = \frac{x+1}{2}$ for all $x \in \mathbb{R}$, find $(g \circ f)(x)$
2. Find the domain of the real function $f(x) = \sqrt{x^2 - 25}$
3. Define symmetric matrix & give an example.
4. If $A = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 3 & 4 \\ 5 & -6 & x \end{bmatrix}$, $\det A = 45$ then find x .
5. If $\overline{OA} = \bar{i} + \bar{j} + \bar{k}$, $\overline{AB} = 3\bar{i} - 2\bar{j} + \bar{k}$, $\overline{BC} = \bar{i} + 2\bar{j} - 2\bar{k}$, $\overline{CD} = 2\bar{i} + \bar{j} + 3\bar{k}$ then find vector $\overline{OD}$
6. Find the vector equation of the plane passing through $\bar{i} - 2\bar{j} + 5\bar{k}$, $-5\bar{j} - \bar{k}$, $-3\bar{i} + 5\bar{j}$
7. If $|\bar{a} + \bar{b}| = |\bar{a} - \bar{b}|$ then find the angle between $\bar{a}$ and $\bar{b}$
8. Find $\sin 330^\circ \cdot \cos 120^\circ + \cos 210^\circ \cdot \sin 300^\circ$
9. If $A - B = \frac{3\pi}{4}$, then show that $(1 - \tan A)(1 + \tan B) = 2$
10. Show that $\tanh^{-1} \frac{1}{2} = \frac{1}{2} \log_e 3$.

SECTION-B

II. Answer any FIVE of the following SAQs:

5 × 4 = 20

11. If $A = \begin{bmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{bmatrix}$ is a non-singular matrix, then prove that A is invertible and $A^{-1} = \frac{\text{Adj}A}{\det A}$
12. If the points whose position vectors are $3\bar{i} - 2\bar{j} - \bar{k}$, $2\bar{i} + 3\bar{j} - 4\bar{k}$, $-\bar{i} + \bar{j} + 2\bar{k}$, $4\bar{i} + 5\bar{j} + \lambda\bar{k}$ are coplanar, then show that $\lambda = -146/17$
13. If $\bar{a} = 2\bar{i} + \bar{j} - \bar{k}$, $\bar{b} = -\bar{i} + 2\bar{j} - 4\bar{k}$, $\bar{c} = \bar{i} + \bar{j} + \bar{k}$ then find $(\bar{a} \times \bar{b}) \cdot (\bar{b} \times \bar{c})$
14. S.T $\cos A \cos\left(\frac{\pi}{3} + A\right) \cos\left(\frac{\pi}{3} - A\right) = \frac{1}{4} \cos 3A$. Hence deduce that $\cos \frac{\pi}{9} \cos \frac{2\pi}{9} \cos \frac{3\pi}{9} \cos \frac{4\pi}{9} = \frac{1}{16}$
15. If $0 < x < \frac{\pi}{2}$ then solve $\cot^2 x - (\sqrt{3} + 1) \cot x + \sqrt{3} = 0$
16. Prove that $\tan^{-1} \frac{1}{2} + \tan^{-1} \frac{1}{5} + \tan^{-1} \frac{1}{8} = \frac{\pi}{4}$.
17. In $\triangle ABC$, show that $\frac{b^2 - c^2}{a^2} = \frac{\sin(B - C)}{\sin(B + C)}$

SECTION-C

III. Answer any FIVE of the following LAQs:

5 × 7 = 35

18. If $f: A \rightarrow B$ is a bijective function then prove that (i) $f \circ f^{-1} = I_B$ (ii) $f^{-1} \circ f = I_A$
19. By using Mathematical Induction, to prove $\frac{1}{1.3} + \frac{1}{3.5} + \frac{1}{5.7} + \dots + \frac{1}{(2n-1)(2n+1)} = \frac{n}{2n+1}$, $\forall n \in \mathbb{N}$
20. Show that $\begin{vmatrix} a & b & c \\ b & c & a \\ c & a & b \end{vmatrix} = \begin{vmatrix} 2bc - a^2 & c^2 & b^2 \\ c^2 & 2ac - b^2 & a^2 \\ b^2 & a^2 & 2ab - c^2 \end{vmatrix} = (a^3 + b^3 + c^3 - 3abc)^2$
21. Solve $2x - y + 3z = 8$, $-x + 2y + z = 4$, $3x + y - 4z = 0$ by using Matrix inversion method.
22. Find the shortest distance between the skew lines $\bar{r} = (6\bar{i} + 2\bar{j} + 2\bar{k}) + t(\bar{i} - 2\bar{j} + 2\bar{k})$ and $\bar{r} = (-4\bar{i} - \bar{k}) + s(3\bar{i} - 2\bar{j} - 2\bar{k})$.
23. If $A + B + C = \frac{\pi}{2}$ then prove that $\cos 2A + \cos 2B + \cos 2C = 1 + 4 \sin A \sin B \sin C$.
24. Prove that $r + r_1 + r_2 - r_3 = 4R \cos C$.

1. If $f(x)=2x-1$, $g(x)=\frac{x+1}{2}$ for all $x \in \mathbb{R}$, find (i) $(g \circ f)(x)$ (ii) $(f \circ g)(x)$

A: (i) $(g \circ f)(x) = g(f(x)) = g(2x-1) = \frac{(2x-1)+1}{2} = \frac{2x}{2} = x$

(ii) $(f \circ g)(x) = f(g(x)) = f\left(\frac{x+1}{2}\right) = 2\left(\frac{x+1}{2}\right) - 1 = x + 1 - 1 = x$

2. Find the domain of the real function $\sqrt{x^2 - 25}$

A: Given $f(x)$ is defined when $x^2 - 25 \geq 0$

$$\Rightarrow (x-5)(x+5) \geq 0$$

$$\Rightarrow x \in (-\infty, -5] \cup [5, \infty)$$

$$\therefore \text{Domain} = (-\infty, -5] \cup [5, \infty)$$

3. Define symmetric matrix & give an example.

A: SYMMETRIC MATRIX: A square matrix A is said to be a Symmetric matrix if $A^T = A$.

Ex: $A = \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix}$, $B = \begin{bmatrix} 1 & 2 & 0 \\ 2 & -3 & -1 \\ 0 & -1 & 4 \end{bmatrix}$, $C = \begin{bmatrix} a & h & g \\ h & b & f \\ g & f & c \end{bmatrix}$

4. If $A = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 3 & 4 \\ 5 & -6 & x \end{bmatrix}$ and $\det A = 45$ then find x .

A: Given $\begin{vmatrix} 1 & 0 & 0 \\ 2 & 3 & 4 \\ 5 & -6 & x \end{vmatrix} = 45$

$$\Rightarrow 1(3x + 24) + 0 + 0 = 45 \Rightarrow 3x = 45 - 24 \Rightarrow 3x = 21 \Rightarrow x = 7 \quad \therefore x = 7$$

5. If $\overrightarrow{OA} = \vec{i} + \vec{j} + \vec{k}$, $\overrightarrow{AB} = 3\vec{i} - 2\vec{j} + \vec{k}$, $\overrightarrow{BC} = \vec{i} + 2\vec{j} - 2\vec{k}$, $\overrightarrow{CD} = 2\vec{i} + \vec{j} + 3\vec{k}$ then find the vector $\overrightarrow{OD}$

A: Consider $\overrightarrow{OA} + \overrightarrow{AB} + \overrightarrow{BC} + \overrightarrow{CD} = (\overrightarrow{OA} + \overrightarrow{AB}) + \overrightarrow{BC} + \overrightarrow{CD} = (\overrightarrow{OB} + \overrightarrow{BC}) + \overrightarrow{CD} = \overrightarrow{OC} + \overrightarrow{CD} = \overrightarrow{OD}$

$$\begin{aligned}\text{Hence } \overrightarrow{OD} &= \overrightarrow{OA} + \overrightarrow{AB} + \overrightarrow{BC} + \overrightarrow{CD} = (\vec{i} + \vec{j} + \vec{k}) + (3\vec{i} - 2\vec{j} + \vec{k}) + (\vec{i} + 2\vec{j} - 2\vec{k}) + (2\vec{i} + \vec{j} + 3\vec{k}) \\ &= 7\vec{i} + 2\vec{j} + 3\vec{k}\end{aligned}$$

6. Find the vector equation of the plane passing through the points $\vec{i} - 2\vec{j} + 5\vec{k}$, $-5\vec{j} - \vec{k}$, $-3\vec{i} + 5\vec{j}$

A: Given $A(\vec{a}) = \vec{i} - 2\vec{j} + 5\vec{k}$,

$$B(\vec{b}) = -5\vec{j} - \vec{k}, \quad C(\vec{c}) = -3\vec{i} + 5\vec{j}$$

Vector equation of the plane is $\vec{r} = (1-s-t)\vec{a} + s\vec{b} + t\vec{c}, s, t \in \mathbb{R}$

$$\therefore \vec{r} = (1-s-t)(\vec{i} - 2\vec{j} + 5\vec{k}) + s(-5\vec{j} - \vec{k}) + t(-3\vec{i} + 5\vec{j}), s, t \in \mathbb{R}$$

7. If $|\vec{a} + \vec{b}| = |\vec{a} - \vec{b}|$ then find the angle between $\vec{a}$ and $\vec{b}$

A: Given that $|\vec{a} + \vec{b}| = |\vec{a} - \vec{b}|$

$$\Rightarrow |\vec{a} + \vec{b}|^2 = |\vec{a} - \vec{b}|^2 \Rightarrow \vec{a}^2 + \vec{b}^2 + 2\vec{a} \cdot \vec{b} = \vec{a}^2 + \vec{b}^2 - 2\vec{a} \cdot \vec{b}$$

$$\Rightarrow 4\vec{a} \cdot \vec{b} = 0 \Rightarrow \vec{a} \cdot \vec{b} = 0 \Rightarrow \vec{a} \perp \vec{b}$$

$\therefore$ Angle between $\vec{a}$ and $\vec{b}$ is 90°

8. Find $\sin 330^\circ \cdot \cos 120^\circ + \cos 210^\circ \cdot \sin 300^\circ$

A: $\sin 330^\circ = \sin(360^\circ - 30^\circ) = -\sin 30^\circ = -1/2$

$$\cos 120^\circ = \cos(180^\circ - 60^\circ) = -\cos 60^\circ = -1/2$$

$$\cos 210^\circ = \cos(180^\circ + 30^\circ) = -\cos 30^\circ = -\sqrt{3}/2$$

$$\sin 300^\circ = \sin(360^\circ - 60^\circ) = -\sin 60^\circ = -\sqrt{3}/2$$

$$\therefore \text{G.E} = \left(-\frac{1}{2}\right)\left(-\frac{1}{2}\right) + \left(-\frac{\sqrt{3}}{2}\right)\left(-\frac{\sqrt{3}}{2}\right) = \frac{1}{4} + \frac{3}{4} = \frac{4}{4} = 1$$

9. If $A - B = \frac{3\pi}{4}$, then show that $(1 - \tan A)(1 + \tan B) = 2$

A: Given $A - B = \frac{3\pi}{4} \Rightarrow \tan(A - B) = \tan \frac{3\pi}{4} \Rightarrow \frac{\tan A - \tan B}{1 + \tan A \tan B} = -1$

$$\Rightarrow \tan A - \tan B = -1 - \tan A \tan B = -\tan A + \tan B - \tan A \tan B = 1 \text{ Adding 1 on both sides}$$

$$\Rightarrow 1 - \tan A + \tan B - \tan A \tan B = 1 + 1$$

$$\Rightarrow (1 - \tan A) - \tan B(1 - \tan A) = 2 \Rightarrow (1 - \tan A)(1 - \tan B) = 2$$

10. Show that $\text{Tanh}^{-1} \frac{1}{2} = \frac{1}{2} \log_e 3$

A: We know $\text{Tanh}^{-1} x = \frac{1}{2} \log_e \left(\frac{1+x}{1-x} \right)$

$$\therefore \text{Tanh}^{-1} \left(\frac{1}{2} \right) = \frac{1}{2} \log_e \left(\frac{1 + \frac{1}{2}}{1 - \frac{1}{2}} \right) = \frac{1}{2} \log_e \left(\frac{\frac{3}{2}}{\frac{1}{2}} \right) = \frac{1}{2} \log_e (3)$$

SECTION-B

11. If A is a non-singular matrix then prove that $A^{-1} = \frac{\text{Adj } A}{\det A}$

A: We take $A = \begin{bmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{bmatrix}$

We take cofactors of $a_1, b_1, c_1, \dots$ as $A_1, B_1, C_1, \dots$

$$\therefore \text{Adj } A = \begin{bmatrix} A_1 & B_1 & C_1 \\ A_2 & B_2 & C_2 \\ A_3 & B_3 & C_3 \end{bmatrix}^T \Rightarrow \text{Adj } A = \begin{bmatrix} A_1 & A_2 & A_3 \\ B_1 & B_2 & B_3 \\ C_1 & C_2 & C_3 \end{bmatrix}$$

$$A \cdot (\text{Adj } A) = \begin{bmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{bmatrix} \begin{bmatrix} A_1 & A_2 & A_3 \\ B_1 & B_2 & B_3 \\ C_1 & C_2 & C_3 \end{bmatrix}$$

$$= \begin{bmatrix} a_1 A_1 + b_1 B_1 + c_1 C_1 & a_1 A_2 + b_1 B_2 + c_1 C_2 & a_1 A_3 + b_1 B_3 + c_1 C_3 \\ a_2 A_1 + b_2 B_1 + c_2 C_1 & a_2 A_2 + b_2 B_2 + c_2 C_2 & a_2 A_3 + b_2 B_3 + c_2 C_3 \\ a_3 A_1 + b_3 B_1 + c_3 C_1 & a_3 A_2 + b_3 B_2 + c_3 C_2 & a_3 A_3 + b_3 B_3 + c_3 C_3 \end{bmatrix}$$

$$= \begin{bmatrix} \det A & 0 & 0 \\ 0 & \det A & 0 \\ 0 & 0 & \det A \end{bmatrix} \quad (\text{From properties of determinants})$$

$$= (\det A) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = (\det A) \cdot I$$

$\therefore A(\text{Adj } A) = (\det A) I$; Similarly, we can prove that $(\text{Adj } A)A = (\det A) I$

$$\therefore A \left(\frac{\text{Adj } A}{\det A} \right) = I \quad (\because \det A \neq 0, \text{ as } A \text{ is non-singular})$$

$$\therefore A^{-1} = \frac{\text{Adj } A}{\det A} \quad [\because AB = I \Rightarrow A^{-1} = B]$$

12. If the points whose position vectors are $3\bar{i} - 2\bar{j} - \bar{k}$, $2\bar{i} + 3\bar{j} - 4\bar{k}$, $-\bar{i} + \bar{j} + 2\bar{k}$, $4\bar{i} + 5\bar{j} + \lambda\bar{k}$ are coplanar, then show that $\lambda = -146/17$

A: We take

$$\overline{OP} = 3\bar{i} - 2\bar{j} - \bar{k}, \overline{OQ} = 2\bar{i} + 3\bar{j} - 4\bar{k},$$

$$\overline{OR} = -\bar{i} + \bar{j} + 2\bar{k}, \overline{OS} = 4\bar{i} + 5\bar{j} + \lambda\bar{k},$$

where 'O' is the origin.

$$\therefore \overline{PQ} = \overline{OQ} - \overline{OP}$$

$$= (2\bar{i} + 3\bar{j} - 4\bar{k}) - (3\bar{i} - 2\bar{j} - \bar{k})$$

$$= -\bar{i} + 5\bar{j} - 3\bar{k}$$

$$\overline{PR} = \overline{OR} - \overline{OP}$$

$$= (-\bar{i} + \bar{j} + 2\bar{k}) - (3\bar{i} - 2\bar{j} - \bar{k})$$

$$= -4\bar{i} + 3\bar{j} + 3\bar{k}$$

$$\overline{PS} = \overline{OS} - \overline{OP}$$

$$= (4\bar{i} + 5\bar{j} + \lambda\bar{k}) - (3\bar{i} - 2\bar{j} - \bar{k})$$

$$= \bar{i} + 7\bar{j} + (\lambda + 1)\bar{k}$$

But, $[\overline{PQ} \overline{PR} \overline{PS}] = 0$ [Since P,Q,R,S are coplanar]

$$\Rightarrow \begin{vmatrix} -1 & 5 & -3 \\ -4 & 3 & 3 \\ 1 & 7 & \lambda + 1 \end{vmatrix} = 0$$

$$\Rightarrow (-1)[3(\lambda + 1) - 21] - 5[-4(\lambda + 1) - 3]$$

$$- 3[(-28) - 3] = 0$$

$$\Rightarrow -1(3\lambda - 18) - 5(-4\lambda - 7) - 3(-31) = 0$$

$$\Rightarrow -3\lambda + 18 + 20\lambda + 35 + 93 = 0$$

$$\Rightarrow -3\lambda + 20\lambda + 35 + 93 + 18 = 0$$

$$\Rightarrow 17\lambda + 146 = 0$$

$$\Rightarrow 17\lambda = -146$$

$$\Rightarrow \lambda = -146/17$$

13. If $\vec{a} = 2\vec{i} + \vec{j} - \vec{k}$, $\vec{b} = -\vec{i} + 2\vec{j} - 4\vec{k}$, $\vec{c} = \vec{i} + \vec{j} + \vec{k}$ then find $(\vec{a} \times \vec{b}) \cdot (\vec{b} \times \vec{c})$

A: Given that $\vec{a} = 2\vec{i} + \vec{j} - \vec{k}$, $\vec{b} = -\vec{i} + 2\vec{j} - 4\vec{k}$ and $\vec{c} = \vec{i} + \vec{j} + \vec{k}$

$$\text{Now } \vec{a} \times \vec{b} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 2 & 1 & -1 \\ -1 & 2 & -4 \end{vmatrix} = \vec{i}(-4+2) - \vec{j}(-8-1) + \vec{k}(4+1) = -2\vec{i} + 9\vec{j} + 5\vec{k}$$

$$\text{Also, } \vec{b} \times \vec{c} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ -1 & 2 & -4 \\ 1 & 1 & 1 \end{vmatrix} = \vec{i}(2+4) - \vec{j}(-1+4) + \vec{k}(-1-2) = 6\vec{i} - 3\vec{j} - 3\vec{k}$$

$$\text{Now } (\vec{a} \times \vec{b}) \cdot (\vec{b} \times \vec{c}) = (-2\vec{i} + 9\vec{j} + 5\vec{k}) \cdot (6\vec{i} - 3\vec{j} - 3\vec{k}) = (-2)(6) + (9)(-3) + 5(-3) = -12 - 27 - 15 = -54$$

$$\therefore (\vec{a} \times \vec{b}) \cdot (\vec{b} \times \vec{c}) = 54$$

14. Show that $\cos A \cos\left(\frac{\pi}{3} + A\right) \cos\left(\frac{\pi}{3} - A\right) = \frac{1}{4} \cos 3A$ Hence deduce that

$$\cos \frac{\pi}{9} \cos \frac{2\pi}{9} \cos \frac{3\pi}{9} \cos \frac{4\pi}{9} = \frac{1}{16}$$

A: L.H.S = $\cos A \cos\left(\frac{\pi}{3} + A\right) \cos\left(\frac{\pi}{3} - A\right) = \cos A \left(\cos^2 \frac{\pi}{3} - \sin^2 A \right)$

$$= \cos A \left[\left(\frac{1}{2}\right)^2 - (1 - \cos^2 A) \right] = \cos A \left[\frac{1}{4} - 1 + \cos^2 A \right]$$

$$= \cos A \left(\frac{1 - 4 + 4\cos^2 A}{4} \right) = \frac{1}{4} \cos A (4\cos^2 A - 3) = \frac{1}{4} [4\cos^3 A - 3\cos A] = \frac{1}{4} \cos 3A = \text{R.H.S}$$

$$\therefore \cos A \cos(60^\circ + A) \cos(60^\circ - A) = \frac{1}{4} \cos 3A$$

$$\text{Put } A = 20^\circ \text{ then } \cos 20^\circ \cos 40^\circ \cos 80^\circ = \frac{1}{4} \cos 60^\circ$$

On multiplying both sides by $\cos 60^\circ$, we get $\cos 20^\circ \cos 40^\circ \cos 60^\circ \cos 80^\circ = \frac{1}{4} \cos^2 60^\circ$

$$\Rightarrow \cos\left(\frac{\pi}{9}\right) \cos\left(\frac{2\pi}{9}\right) \cos\left(\frac{3\pi}{9}\right) \cos\left(\frac{4\pi}{9}\right) = \frac{1}{4} \left(\frac{1}{2}\right)^2 = \frac{1}{16}$$

15. If $0 < x < \frac{\pi}{2}$ then solve $\cot^2 x - (\sqrt{3} + 1)\cot x + \sqrt{3} = 0$

A: Given that $\cot^2 x - (\sqrt{3} + 1)\cot x + \sqrt{3} = 0 \Rightarrow \cot^2 x - \sqrt{3}\cot x - \cot x + \sqrt{3} = 0$

$$\Rightarrow \cot x(\cot x - \sqrt{3}) - (\cot x - \sqrt{3}) = 0 \Rightarrow (\cot x - 1)(\cot x - \sqrt{3}) = 0$$

$$\Rightarrow \cot x - 1 = 0 \text{ (or) } \cot x - \sqrt{3} = 0 \Rightarrow \cot x = 1 \text{ (or) } \cot x = \sqrt{3}$$

$$\Rightarrow \tan x = 1 \text{ (or) } \tan x = \frac{1}{\sqrt{3}}$$

$$\tan x = 1 = \tan \frac{\pi}{4} \Rightarrow x = \frac{\pi}{4}; \left[\because 0 < x < \frac{\pi}{2} \right]$$

$$\tan x = \frac{1}{\sqrt{3}} = \tan \frac{\pi}{6} \Rightarrow x = \frac{\pi}{6}$$

$$\therefore \text{The solutions are } x = \frac{\pi}{4}, \frac{\pi}{6}$$

16. Prove that $\tan^{-1} \frac{1}{2} + \tan^{-1} \frac{1}{5} + \tan^{-1} \frac{1}{8} = \frac{\pi}{4}$

A: We know, $\tan^{-1} x + \tan^{-1} y = \tan^{-1} \left(\frac{x+y}{1-xy} \right)$

$$\therefore \tan^{-1} \frac{1}{2} + \tan^{-1} \frac{1}{5} = \tan^{-1} \left(\frac{\frac{1}{2} + \frac{1}{5}}{1 - \frac{1}{2} \cdot \frac{1}{5}} \right) = \tan^{-1} \left(\frac{\frac{5+2}{10}}{\frac{10-1}{10}} \right) = \tan^{-1} \frac{7}{9}$$

$$\therefore \text{L.H.S} = \tan^{-1} \frac{7}{9} + \tan^{-1} \frac{1}{8} = \tan^{-1} \left(\frac{\frac{7}{9} + \frac{1}{8}}{1 - \frac{7}{9} \cdot \frac{1}{8}} \right) = \tan^{-1} \left(\frac{\frac{56+9}{72}}{\frac{72-7}{72}} \right)$$

$$= \tan^{-1} \left(\frac{65}{65} \right) = \tan^{-1} 1 = \frac{\pi}{4} = \text{R.H.S}$$

17. In $\triangle ABC$, show that $\frac{b^2 - c^2}{a^2} = \frac{\sin(B - C)}{\sin(B + C)}$

$$\text{A: L.H.S} = \frac{b^2 - c^2}{a^2} = \frac{(2R \sin B)^2 - (2R \sin C)^2}{(2R \sin A)^2} = \frac{4R^2(\sin^2 B - \sin^2 C)}{4R^2 \sin^2 A}$$

$$= \frac{\sin^2 B - \sin^2 C}{\sin^2 A} = \frac{\cancel{\sin(B+C)} \sin(B-C)}{\cancel{\sin^2(B+C)}} = \frac{\sin(B-C)}{\sin(B+C)} = \text{R.H.S}$$

SECTION-C

18. If $f:A \rightarrow B$ is a bijective function then prove that (i) $f \circ f^{-1} = I_B$ (ii) $f^{-1} \circ f = I_A$

A: (i) To prove that $f \circ f^{-1} = I_B$

Part-1 : Given $f:A \rightarrow B$ is a bijective function, then $f^{-1}: B \rightarrow A$ is also a bijection

$$\therefore f \circ f^{-1}: B \rightarrow B$$

We know, $I_B: B \rightarrow B$

So, $f \circ f^{-1}$ and I_B , both have same domain B

Part-2: For $b \in B$, $(f \circ f^{-1})(b) = f[f^{-1}(b)]$

$$= f(a) \quad [\because f:A \rightarrow B \text{ is bijection} \Rightarrow f(a)=b \Rightarrow f^{-1}(b)=a, \text{ for } a \in A]$$

$$= b = I_B(b) \quad [\because I_B(b)=b, \text{ for } b \in B]$$

Hence we proved that $f \circ f^{-1} = I_B$

(ii) To prove that $f^{-1} \circ f = I_A$

Part-1: Given $f:A \rightarrow B$ is a bijective function, then $f^{-1}: B \rightarrow A$ is also a bijection

$$\therefore f^{-1} \circ f: A \rightarrow A$$

We know $I_A: A \rightarrow A$

So, $f^{-1} \circ f$ and I_A , both have same domain A

Part-2: for $a \in A$, $(f^{-1} \circ f)(a) = f^{-1}[f(a)]$

$$= f^{-1}(b) = a \quad [\because f:A \rightarrow B \text{ is a bijection} \Rightarrow f(a)=b \Rightarrow f^{-1}(b)=a]$$

$$= I_A(a) \quad [\because I_A(a)=a, \text{ for } a \in A]$$

Hence we proved that $f^{-1} \circ f = I_A$

19. By using Mathematical Induction, Show that $\frac{1}{1.3} + \frac{1}{3.5} + \frac{1}{5.7} + \dots + n \text{ terms} = \frac{n}{2n+1}$

A: To find n^{th} term:

1, 3, 5... are in A.P with $a=1, d=2$

$$\therefore T_n = a + (n-1)d \Rightarrow T_n = 1 + (n-1)2 = 1 + 2n - 2 = 2n - 1$$

3, 5, 7... are in A.P with $a=3, d=2$

$$\therefore T_n = 3 + (n-1)2 = 3 + 2n - 2 = 2n + 1$$

$$\therefore n^{\text{th}} \text{ term is } T_n = \frac{1}{(2n-1)(2n+1)}$$

$$\text{Let } S(n) : \frac{1}{1.3} + \frac{1}{3.5} + \frac{1}{5.7} + \dots + \frac{1}{(2n-1)(2n+1)} = \frac{n}{2n+1}$$

$$\text{Step 1: L.H.S of } S(1) = \frac{1}{1.3} = \frac{1}{3};$$

$$\text{R.H.S of } S(1) = \frac{1}{2.1+1} = \frac{1}{3}$$

$$\therefore \text{L.H.S} = \text{R.H.S.}$$

So, $S(1)$ is true

Step 2: Assume that $S(k)$ is true, for $k \in \mathbb{N}$

$$S(k) : \frac{1}{1.3} + \frac{1}{3.5} + \frac{1}{5.7} + \dots + \frac{1}{(2k-1)(2k+1)} = \frac{k}{2k+1} \quad \dots (1)$$

Step 3: We show that $S(k+1)$ is true

$$(k+1)^{\text{th}} \text{ term} = \frac{1}{(2(k+1)-1)(2(k+1)+1)} = \frac{1}{(2k+1)(2k+3)}$$

On adding $(k+1)^{\text{th}}$ term to both sides of (1), we get

$$\begin{aligned} \text{L.H.S} &= \left[\frac{1}{1.3} + \frac{1}{3.5} + \frac{1}{5.7} + \dots + \frac{1}{(2k-1)(2k+1)} \right] + \frac{1}{(2k+1)(2k+3)} \\ &= \frac{k}{2k+1} + \frac{1}{(2k+1)(2k+3)} = \frac{k(2k+3)+1}{(2k+1)(2k+3)} = \frac{2k^2+3k+1}{(2k+1)(2k+3)} \\ &= \frac{(k+1)\cancel{(2k+1)}}{\cancel{(2k+1)}(2k+3)} = \frac{k+1}{2k+3} = \frac{k+1}{2k+2+1} = \frac{k+1}{2(k+1)+1} = \text{R.H.S} \end{aligned}$$

$$\therefore \text{L.H.S} = \text{R.H.S.}$$

So, $S(k+1)$ is true whenever $S(k)$ is true

Hence, by P.M.I the given statement is true, for all $n \in \mathbb{N}$

20. Show that
$$\begin{vmatrix} a & b & c \\ b & c & a \\ c & a & b \end{vmatrix}^2 = \begin{vmatrix} 2bc-a^2 & c^2 & b^2 \\ c^2 & 2ac-b^2 & a^2 \\ b^2 & a^2 & 2ab-c^2 \end{vmatrix} = (a^3+b^3+c^3-3abc)^2$$

A: We take $\Delta = \begin{vmatrix} a & b & c \\ b & c & a \\ c & a & b \end{vmatrix}$

$$= a(bc - a^2) - b(b^2 - ac) + c(ab - c^2)$$

$$= abc - a^3 - b^3 + abc + abc - c^3$$

$$= -(a^3 + b^3 + c^3 - 3abc)$$

$$\Rightarrow \Delta^2 = (a^3 + b^3 + c^3 - 3abc)^2 \dots\dots\dots(1)$$

Again $\begin{vmatrix} a & b & c \\ b & c & a \\ c & a & b \end{vmatrix}^2 = \begin{vmatrix} a & b & c \\ b & c & a \\ c & a & b \end{vmatrix} \begin{vmatrix} a & b & c \\ b & c & a \\ c & a & b \end{vmatrix}$

On applying C_{23} on the first determinant, we get

$$= - \begin{vmatrix} a & c & b \\ b & a & c \\ c & b & a \end{vmatrix} \begin{vmatrix} a & b & c \\ b & c & a \\ c & a & b \end{vmatrix}$$

$$= \begin{vmatrix} -a & c & b \\ -b & a & c \\ -c & b & a \end{vmatrix} \begin{vmatrix} a & b & c \\ b & c & a \\ c & a & b \end{vmatrix}$$

$$= \begin{vmatrix} -a^2 + cb + bc & \cancel{ab} + c^2 - \cancel{ab} & \cancel{ac} + \cancel{ac} + b^2 \\ \cancel{ab} - \cancel{ab} + c^2 & -b^2 + ac + ca & \cancel{bc} + a^2 - \cancel{cb} \\ \cancel{ca} + b^2 - \cancel{ac} & \cancel{cb} - \cancel{bc} + a^2 & -c^2 + ba + ab \end{vmatrix}$$

$$= \begin{vmatrix} 2bc - a^2 & c^2 & b^2 \\ c^2 & 2ac - b^2 & a^2 \\ b^2 & a^2 & 2ab - c^2 \end{vmatrix} \dots\dots\dots(2)$$

From (1) and (2), the given result is proved.

21. By using Matrix inversion method, $2x-y+3z=8$, $-x+2y+z=4$, $3x+y-4z=0$

A: The matrix equation corresponding to the given system of equations be $AX=D$, where

$$A = \begin{bmatrix} 2 & -1 & 3 \\ -1 & 2 & 1 \\ 3 & 1 & -4 \end{bmatrix}; X = \begin{bmatrix} x \\ y \\ z \end{bmatrix}, D = \begin{bmatrix} 8 \\ 4 \\ 0 \end{bmatrix}$$

$\therefore$ The solution of $AX=D$ is $X=A^{-1}D$

First we find A^{-1}

$$|A| = \begin{vmatrix} 2 & -1 & 3 \\ -1 & 2 & 1 \\ 3 & 1 & -4 \end{vmatrix} = 2(-8-1) + 1(4-3) + 3(-1-6) = 2(-9) + 1(1) + 3(-7) = -18+1-21 = -38 \neq 0$$

The co-factor matrix of A is

$$\begin{bmatrix} + \begin{vmatrix} 2 & 1 \\ 1 & -4 \end{vmatrix} & - \begin{vmatrix} -1 & 1 \\ 3 & -4 \end{vmatrix} & + \begin{vmatrix} -1 & 2 \\ 3 & 1 \end{vmatrix} \\ - \begin{vmatrix} -1 & 3 \\ 1 & -4 \end{vmatrix} & + \begin{vmatrix} 2 & 3 \\ 3 & -4 \end{vmatrix} & - \begin{vmatrix} 2 & -1 \\ 3 & 1 \end{vmatrix} \\ + \begin{vmatrix} -1 & 3 \\ 2 & 1 \end{vmatrix} & - \begin{vmatrix} 2 & 3 \\ -1 & 1 \end{vmatrix} & + \begin{vmatrix} 2 & -1 \\ -1 & 2 \end{vmatrix} \end{bmatrix} = \begin{bmatrix} (-8-1) & -(4-3) & (-1-6) \\ -(4-3) & (-8-9) & -(2+3) \\ (-1-6) & -(2+3) & (4-1) \end{bmatrix} = \begin{bmatrix} -9 & -1 & -7 \\ -1 & -17 & -5 \\ -7 & -5 & 3 \end{bmatrix}$$

$$\therefore \text{Adj } A = \begin{bmatrix} -9 & -1 & -7 \\ -1 & -17 & -5 \\ -7 & -5 & 3 \end{bmatrix}$$

$$\therefore A^{-1} = \frac{1}{\det A} (\text{Adj } A) = \frac{1}{-38} \begin{bmatrix} -9 & -1 & -7 \\ -1 & -17 & -5 \\ -7 & -5 & 3 \end{bmatrix}$$

$$\text{Now, } X = A^{-1}D = \frac{-1}{38} \begin{bmatrix} -9 & -1 & -7 \\ -1 & -17 & -5 \\ -7 & -5 & 3 \end{bmatrix} \begin{bmatrix} 8 \\ 4 \\ 0 \end{bmatrix} = \frac{-1}{38} \begin{bmatrix} -72-4-0 \\ -8-68-0 \\ -56-20-0 \end{bmatrix} = \frac{-1}{38} \begin{bmatrix} -76 \\ -76 \\ -76 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix}$$

$$\therefore X = \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix}$$

Hence the solution is $x=2, y=2, z=2$

22. Find the shortest distance between the skew lines

$$\vec{r} = (6\vec{i} + 2\vec{j} + 2\vec{k}) + t(\vec{i} - 2\vec{j} + 2\vec{k}) \text{ and } \vec{r} = (-4\vec{i} - \vec{k}) + s(3\vec{i} - 2\vec{j} - 2\vec{k})$$

A: Given skew lines $\vec{r} = (6\vec{i} + 2\vec{j} + 2\vec{k}) + t(\vec{i} - 2\vec{j} + 2\vec{k})$; $\vec{r} = (-4\vec{i} - \vec{k}) + s(3\vec{i} - 2\vec{j} - 2\vec{k})$

Formula: For the skew lines $\vec{r} = \vec{a} + t\vec{b}$, $\vec{r} = \vec{c} + s\vec{d}$ shortest distance(SD) = $\frac{|(\vec{a} - \vec{c}) \cdot (\vec{b} \times \vec{d})|}{|\vec{b} \times \vec{d}|}$

On comparing the given skew lines with $\vec{r} = \vec{a} + t\vec{b}$; $\vec{r} = \vec{c} + s\vec{d}$ we get

$$\vec{a} = 6\vec{i} + 2\vec{j} + 2\vec{k} \text{ and } \vec{b} = \vec{i} - 2\vec{j} + 2\vec{k}$$

$$\text{Also, } \vec{c} = -4\vec{i} - \vec{k} \text{ and } \vec{d} = 3\vec{i} - 2\vec{j} - 2\vec{k}$$

$$\text{So, } \vec{a} - \vec{c} = (6\vec{i} + 2\vec{j} + 2\vec{k}) - (-4\vec{i} - \vec{k}) = 10\vec{i} + 2\vec{j} + 3\vec{k}$$

$$\vec{b} \times \vec{d} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & -2 & 2 \\ 3 & -2 & -2 \end{vmatrix} = \vec{i}(4+4) - \vec{j}(-2-6) + \vec{k}(-2+6) = 8\vec{i} + 8\vec{j} + 4\vec{k}$$

$$\therefore (\vec{a} - \vec{c}) \cdot (\vec{b} \times \vec{d}) = (10\vec{i} + 2\vec{j} + 3\vec{k}) \cdot (8\vec{i} + 8\vec{j} + 4\vec{k}) = 80 + 16 + 12 = 108$$

$$\text{Also, } |\vec{b} \times \vec{d}| = \sqrt{8^2 + 8^2 + 4^2} = \sqrt{64 + 64 + 16} = \sqrt{144} = 12$$

$$\therefore \text{Shortest distance(SD)} = \frac{|(\vec{a} - \vec{c}) \cdot (\vec{b} \times \vec{d})|}{|\vec{b} \times \vec{d}|} = \frac{108}{12} = 9$$

23. If $A+B+C=\frac{\pi}{2}$ then prove that $\cos 2A + \cos 2B + \cos 2C = 1 + 4\sin A \sin B \sin C$.

A: L.H.S = $\cos 2A + \cos 2B + \cos 2C = 2\cos\left(\frac{2A+2B}{2}\right)\cos\left(\frac{2A-2B}{2}\right) + \cos 2C$

$$= 2\cos(A+B)\cos(A-B) + \cos 2C = 2\cos\left(\frac{\pi}{2} - C\right)\cos(A-B) + \cos 2C$$

$$= 2\sin C \cos(A-B) + (1 - 2\sin^2 C) [\because \cos 2\theta = 1 - 2\sin^2 \theta]$$

$$= 1 + 2\sin C [\cos(A-B) - \sin C] = 1 + 2\sin C [\cos(A-B) - \sin\left(\frac{\pi}{2} - (A+B)\right)]$$

$$= 1 + 2\sin C [\cos(A-B) - \cos(A+B)] = 1 + 2\sin C [2\sin A \sin B]$$

$$= 1 + 4\sin A \sin B \sin C = \text{R.H.S}$$

24. Prove that $r + r_1 + r_2 - r_3 = 4R\cos C$

A: L.H.S = $r + r_1 + r_2 - r_3 = (r + r_1) + (r_2 - r_3)$

$$= \left(4R \sin \frac{A}{2} \sin \frac{B}{2} \sin \frac{C}{2} + 4R \sin \frac{A}{2} \cos \frac{B}{2} \cos \frac{C}{2} \right) + \left(4R \cos \frac{A}{2} \sin \frac{B}{2} \cos \frac{C}{2} - 4R \cos \frac{A}{2} \cos \frac{B}{2} \sin \frac{C}{2} \right)$$

$$= 4R \sin \frac{A}{2} \left(\sin \frac{B}{2} \sin \frac{C}{2} + \cos \frac{B}{2} \cos \frac{C}{2} \right) + 4R \cos \frac{A}{2} \left(\sin \frac{B}{2} \cos \frac{C}{2} - \cos \frac{B}{2} \sin \frac{C}{2} \right)$$

$$= 4R \sin \frac{A}{2} \cos \left(\frac{B}{2} - \frac{C}{2} \right) + 4R \cos \frac{A}{2} \sin \left(\frac{B}{2} - \frac{C}{2} \right)$$

$$= 4R \left[\sin \frac{A}{2} \cos \left(\frac{B}{2} - \frac{C}{2} \right) + \cos \frac{A}{2} \sin \left(\frac{B}{2} - \frac{C}{2} \right) \right]$$

$$= 4R \sin \left[\frac{A}{2} + \frac{B}{2} - \frac{C}{2} \right]$$

$$\left[\because A + B + C = 180^\circ \Rightarrow \frac{A}{2} + \frac{B}{2} + \frac{C}{2} = 90^\circ \right]$$

$$= 4R \sin(90^\circ - C) = 4R \cos C = \text{R.H.S}$$